



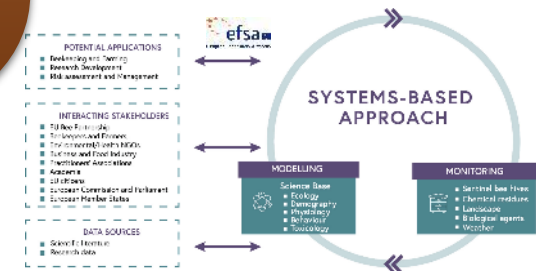
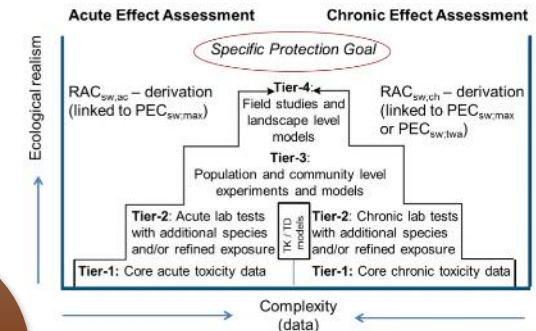
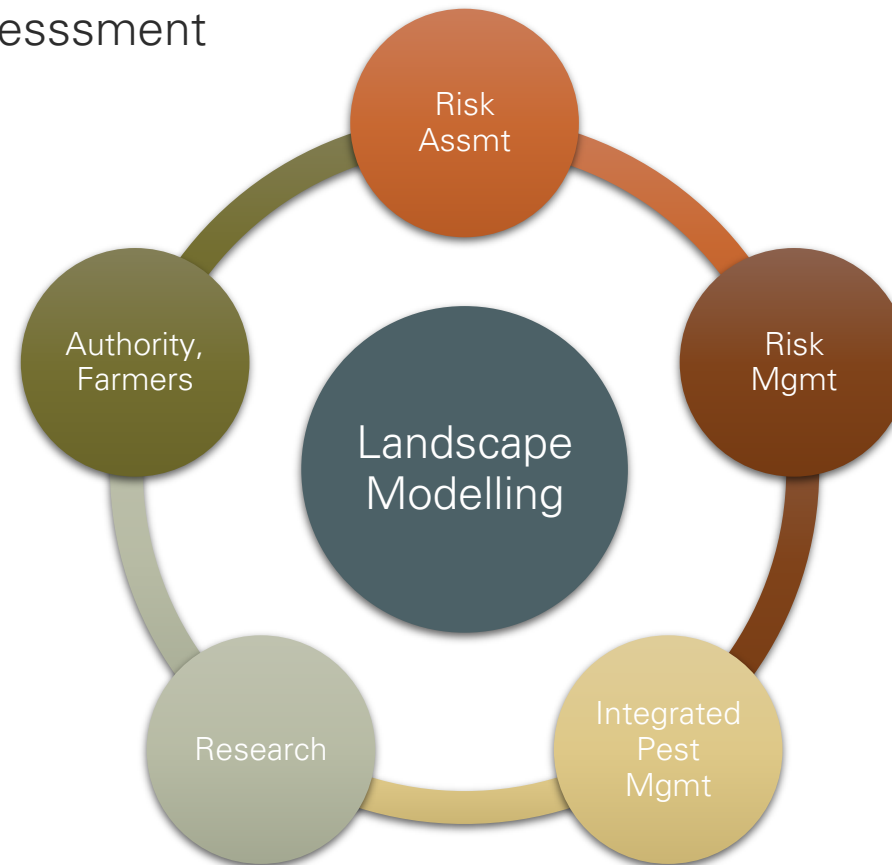
Thorsten Schad (thorsten.schad@landwerk-ev.de)
Sascha Bub (Sascha.bub@rptu.de)
Julian Heinrich (julian.Heinrich@bayer.com)

xLandscape

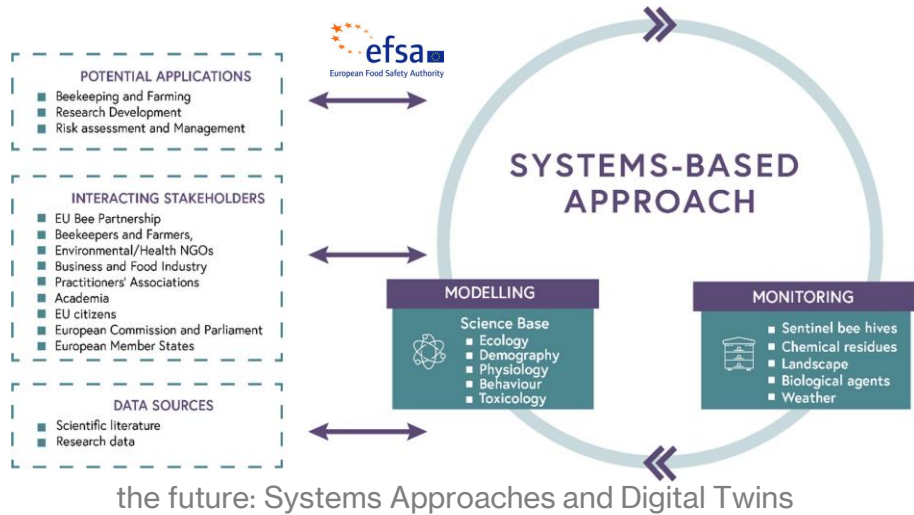
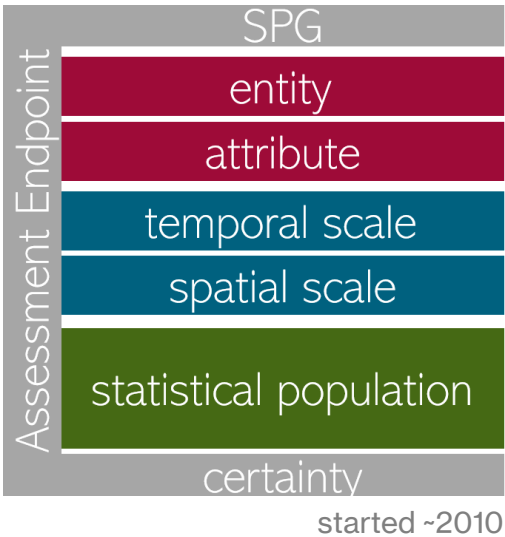
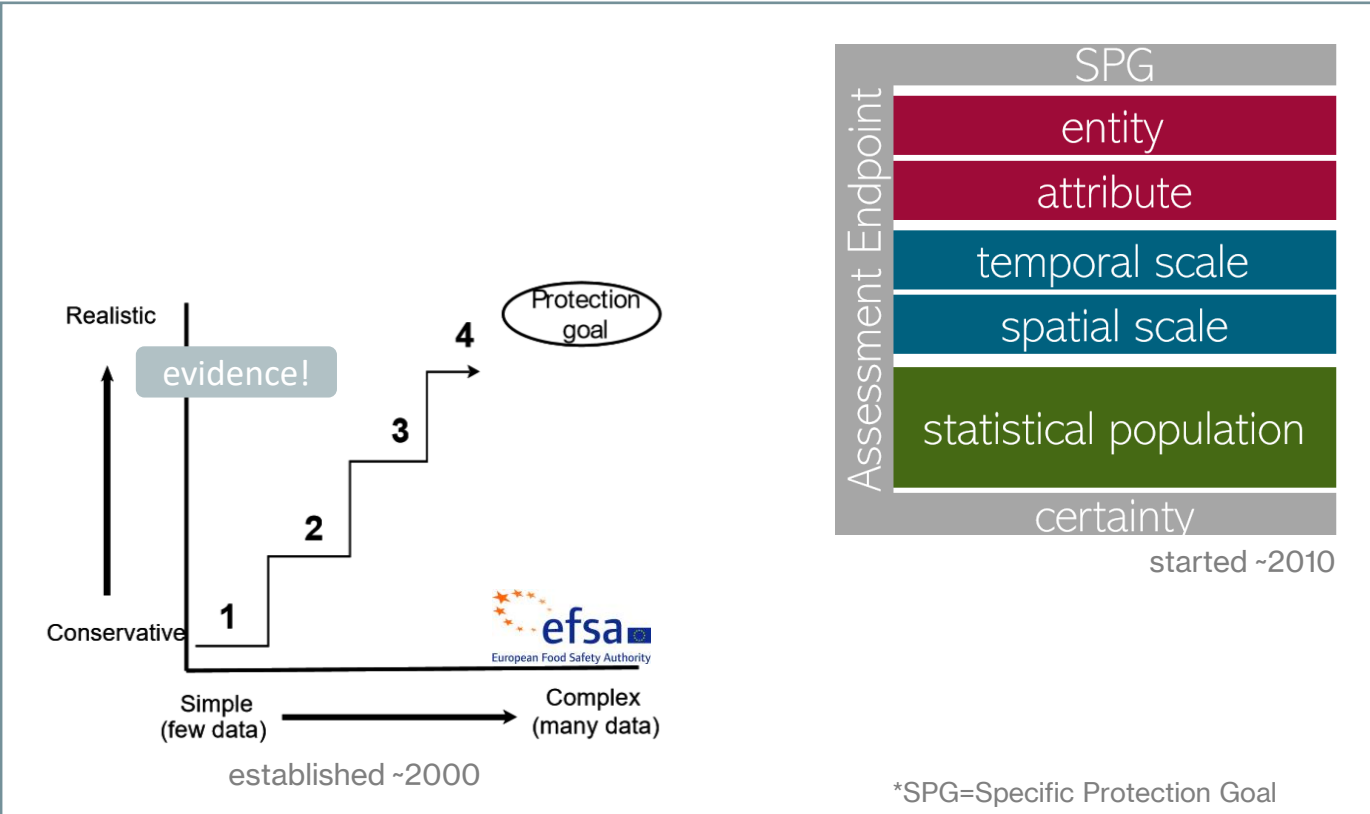
Modular Landscape Models

Demand for Landscape Modelling

- › More realistic, higher-tier risk assessment
EFSA: Reference scenario in tiered schemes
- › Improved integration of processes
- › **Holistic view** to pesticide risk, eg,
 - › multiple stressors, recovery, **biodiversity**
 - › **indirect effects** of weed control
 - › integration of **monitoring** and modelling
- › **Digital Agriculture**
integrated pest control & environmental risk
- › **Digital Twins** (eg, DestinE) - what if..

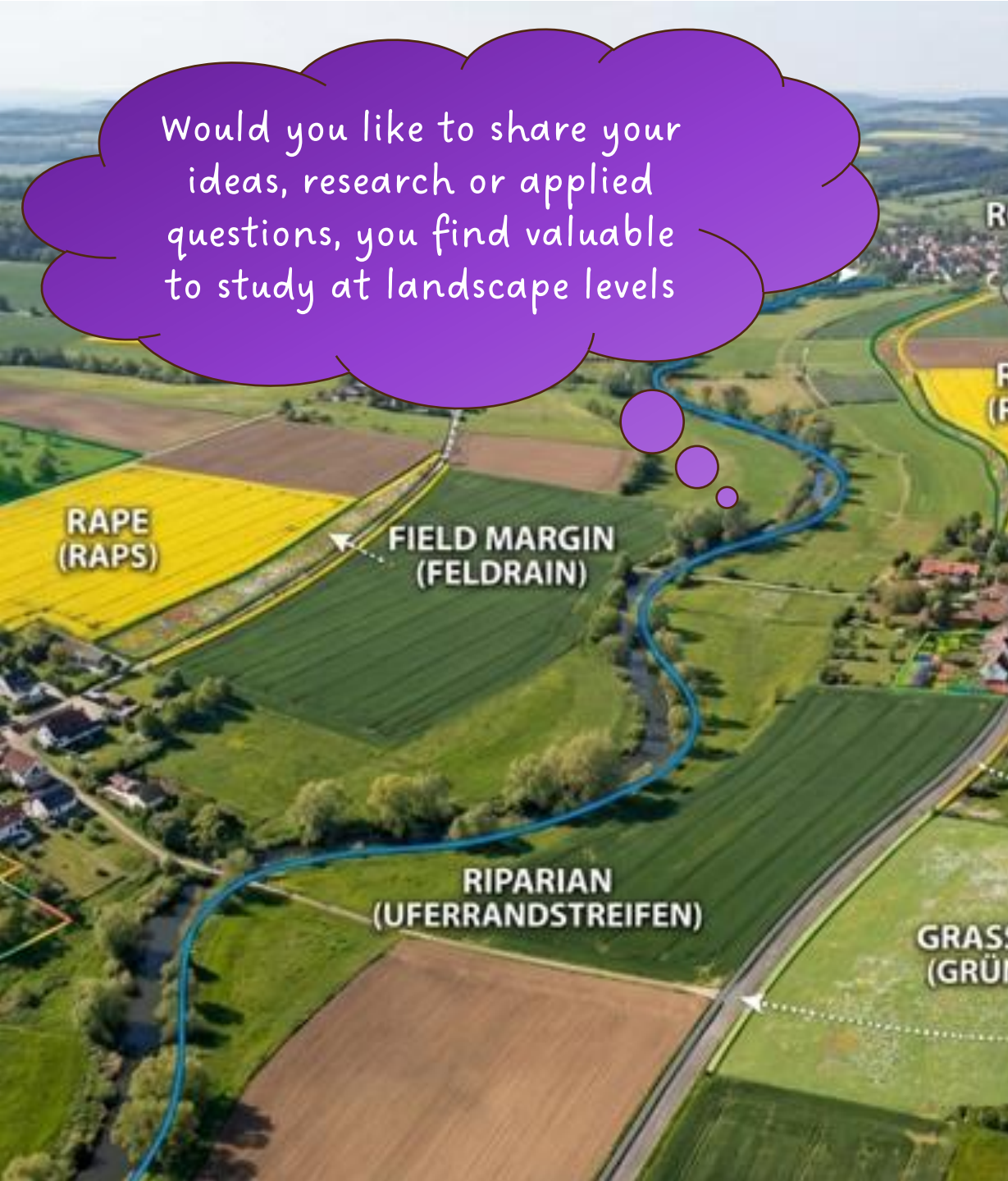


Drivers for the xLandscape Development



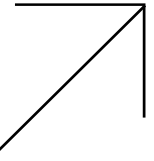
Key concepts driving the xLandscape design:

- **Tiered approach** → flexibility, **adaptivity**, 'get only as complex as necessary'
- **Specific Protection Goals** → operate in explicit **dimensions** and **scales** (spatial, temporal), explicit **structure** of analysis and communication



Would you like to share your ideas, research or applied questions, you find valuable to study at landscape levels

Imagine



you are developing a **new species effect model** (eg, amphibian, wild pollinator, beetle) for pesticide risk assessment or conservation.

- you are interested in **multiple pesticide** exposure and effects across large regions
- you want to **compare risks** of pest control for different **baseline** assumptions
- you study real-world effects of different **risk management** and **landscape design** options
- you want to build a **regional scenario** (or digital twin) to study protection goals and ecosystem services
- you want this work **consistent** with related projects

if you do this from scratch, it's **quite an effort**

now imagine **you can focus on your craft and can make use of open shared work of your colleagues**

Imagine...

Our Vision - why we develop

You have a tool at hand **enabling you to build and run processes and models at landscape-level, using real-world data.**

You can **adapt** this tool to your problem. It's open source.

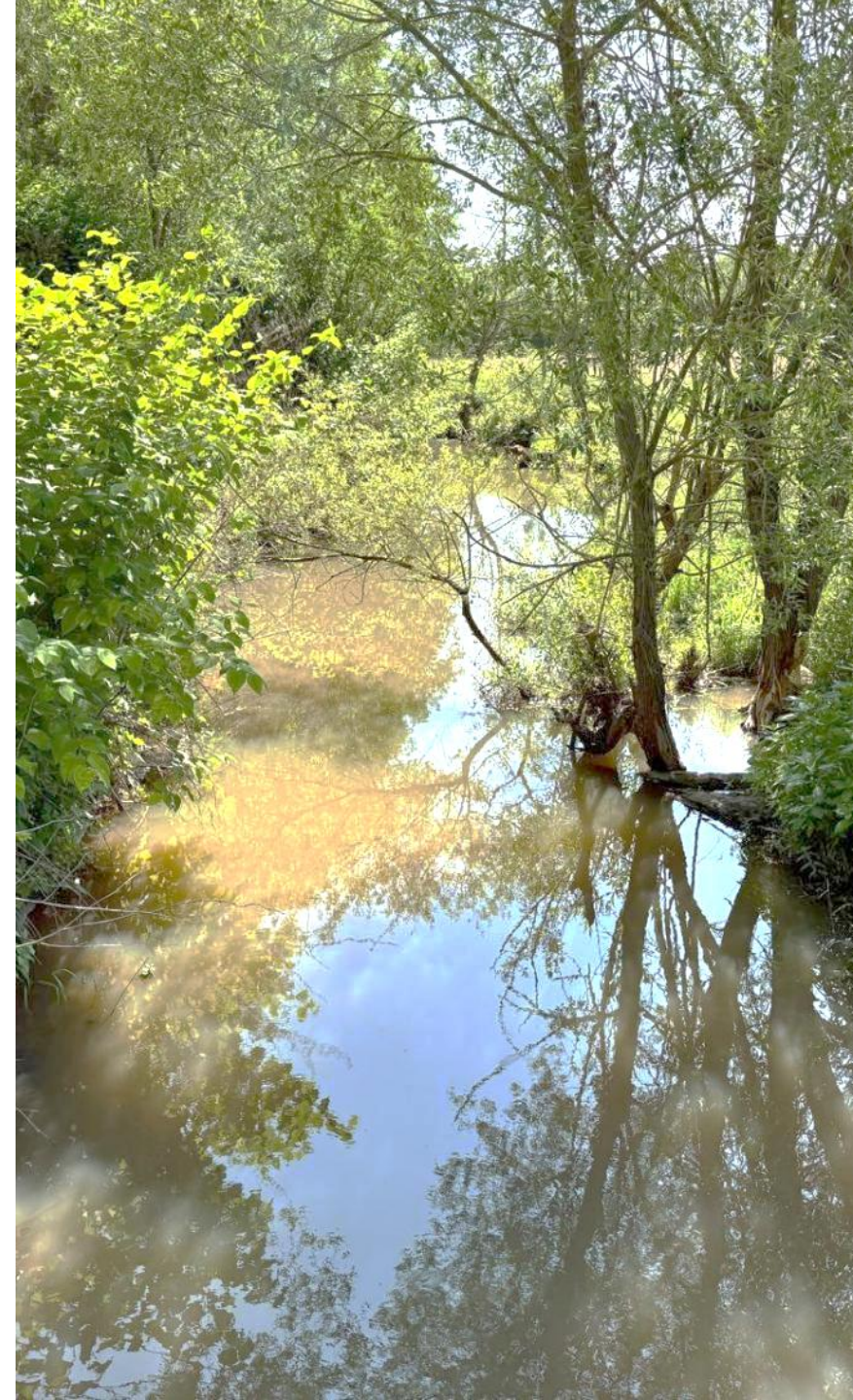
You can make use of open developments done by your **colleagues.**

You can run the landscapes models on your **laptop or large cloud** systems.

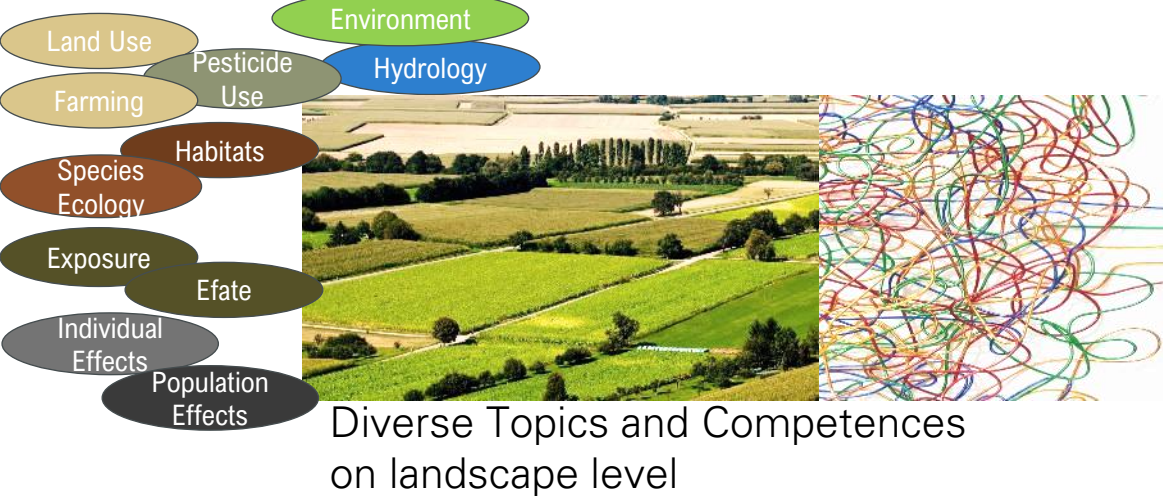
The **conceptual foundation** of the tool is embedded into regulatory-scientific frameworks. It also comes with **tiered scenario development**, allowing you to **start quickly** on screening levels and to get more detailed as you proceed. **Scenario services** support you on request.

You can keep **consistency, freeze and versioning a certain status** for full long-term availability and **reproducibility with a regulatory context.**

→ this is why we think an **open, modular and collaborative landscape modelling framework** is the route to take (→xLandscape)



Modularity enables



do you share positive effects of modularisation?!

Collaboration

Focus on key expertise
Build on existing work



Harmonisation

use similar solutions to similar problems

Transparency

Stepwise Validation
Flexibility – adapt model complexity

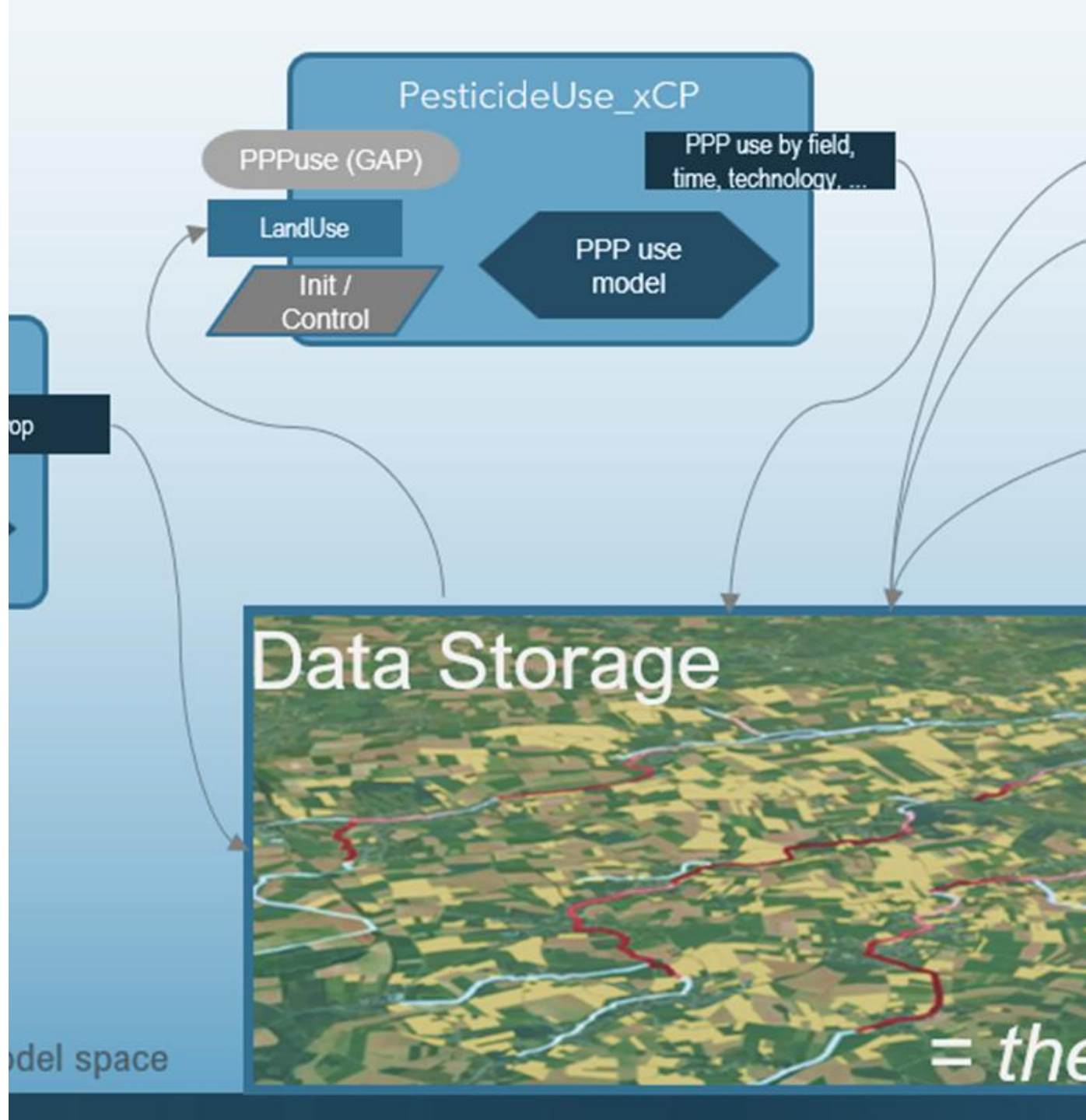
Consistent Integration

use established models
moduls can become certificated APIs*

*Application Programming Interfaces

why
do we develop
a modular
landscape
modelling
framework

simply,
because there is a **demand**
and there is
nothing like this available

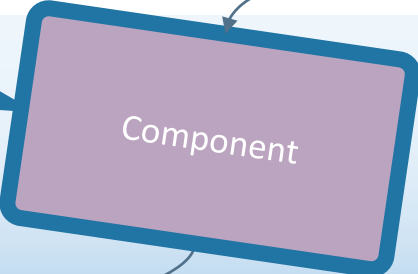


Model Composition: Components

R C++
 Python *Model* Fortran
 Smalltalk Java ...

Components integrate models

- Interface
- Control
- Semantics
- 4 integration levels



PPP use

Toxswa

PRZM5

xDrift

Spatiotemporally explicit Modeling Framework
 Interfaces ▪ Control ▪ MonteCarlo ▪ Dimensions ▪ Scales ▪ Semantics

```

<?xml version="1.0" encoding="utf-8"?>
<!--
  Observers
-->
<observers>
  <Store module="stores" class="X3dStore"/>
</observers>
<!--
  Global
-->
<global>
  <SimulationStart>2000-01-01</SimulationStart>
  <SimulationEnd>2010-12-31</SimulationEnd>
</global>
<!--
  Composition
-->
<composition>
  <Weather module="components" class="HumidWeather"/>
  <LandscapeScenario module="components" class="LandscapeScenario"/>
  <PPM module="components" class="PpmLander"/>
  <SprayDrift module="components" class="SprayDrift" enabled="${(SimulationSprayDriftExposure)}"/>
  <HumidPesticide module="components" class="HumidPesticide" enabled="${(SimulationHumidPesticideExposure)}"/>
  <EnvironmentalRate module="components" class="EnvironmentalRate"/>
  <SprayDriftExposure>
    <FromOutput component="SprayDrift" output="Exposure" enabled="${(SimulationSprayDriftExposure)}"/>
  </SprayDriftExposure>
  <RunOffExposure>
    <FromOutput component="HumidPesticide" output="Exposure" enabled="${(SimulationRunOffExposure)}"/>
  </RunOffExposure>
  <EnvironmentalRate>
    <GlobalType class="Global" unit="g" scales="global" value="${(SimulationEnvironmentalRate)}"/>
  </EnvironmentalRate>
  <DepositionToSoil module="components" class="DepositionToSoil"/>
  <DeleteFolder module="components" class="DeleteFolder"/>
</composition>
</?xml>

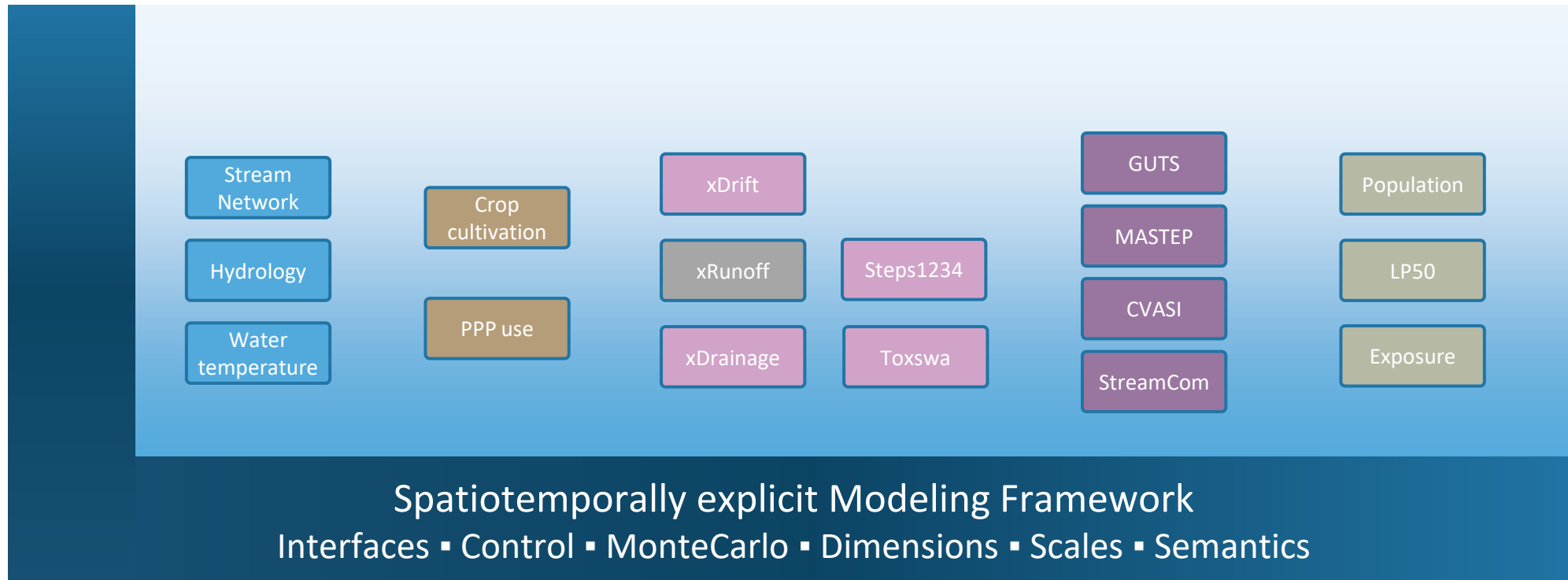
```

xml-based composition

The Modelling Approach

xAquaticRisk

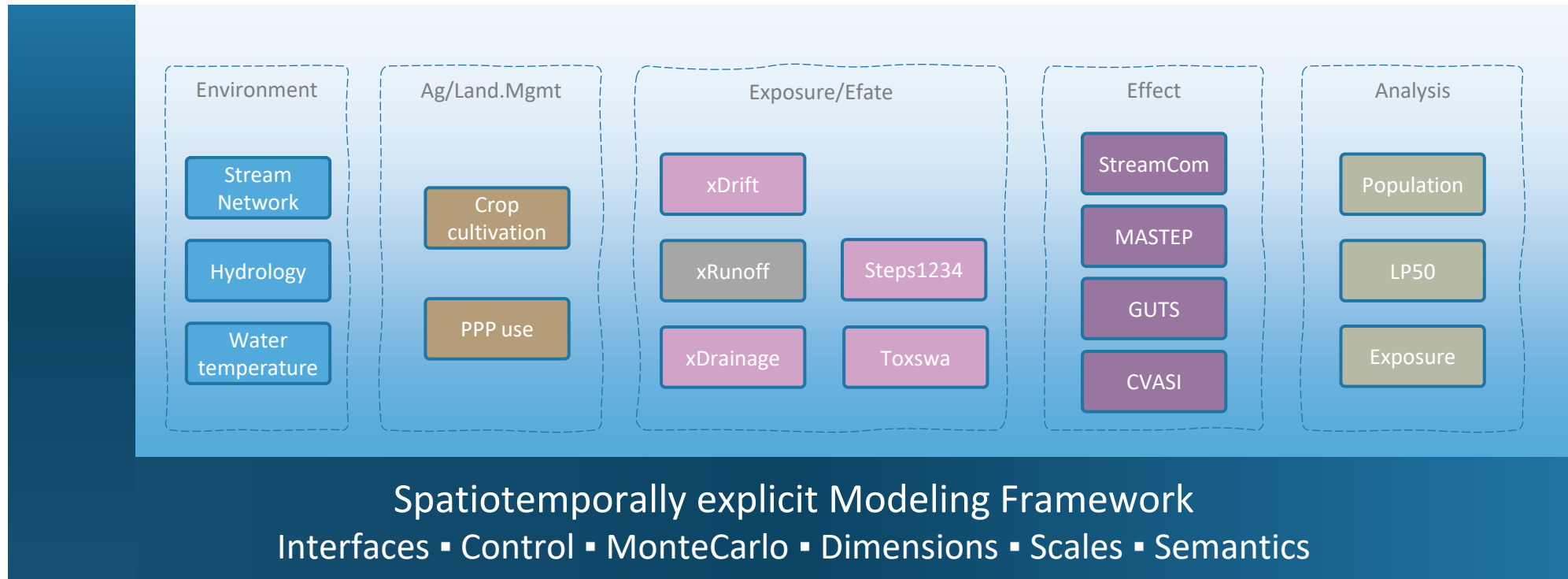
- ✓ **Modular**
- ✓ **Open Source, FAIR**
- ✓ **Makes use of regulatory established models**
- ✓ **Flexible, adaptable**



The Modelling Approach

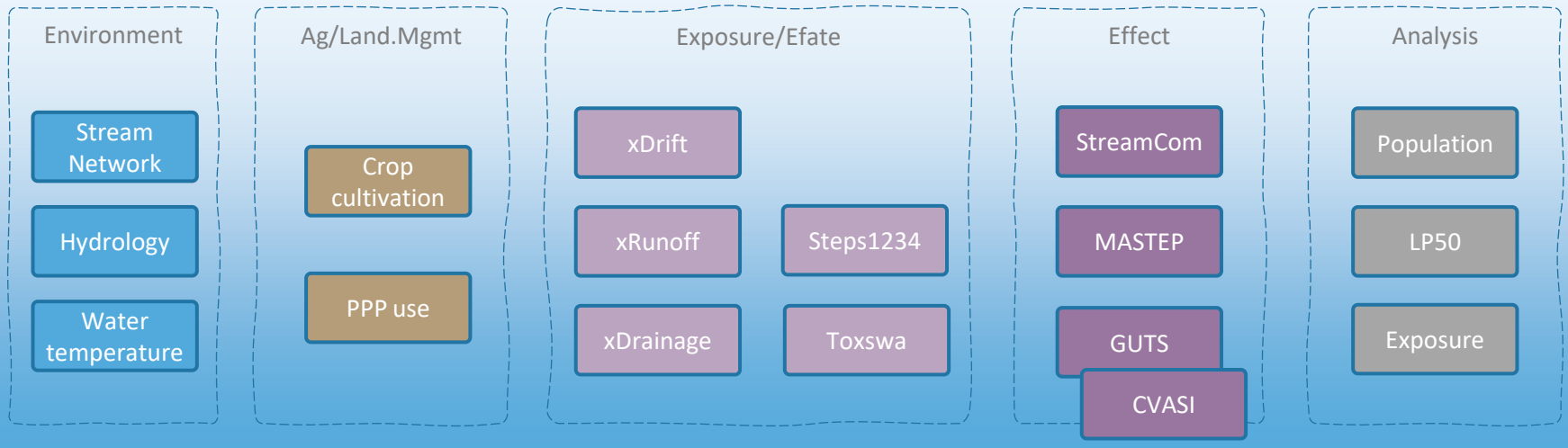
xAquaticRisk

- ✓ Modular
- ✓ Open Source, FAIR
- ✓ Makes use of regulatory established models
- ✓ Flexible, adaptable



Model Composition → xAquaticRisk

User interacts with a single model



Spatiotemporally explicit Modeling Framework
 Interfaces ▪ Control ▪ MonteCarlo ▪ Dimensions ▪ Scales ▪ Semantics

Land use/cover Weather, soil, elevation Topographic, hydrographic Agriculture, PPP use

OS / Cloud

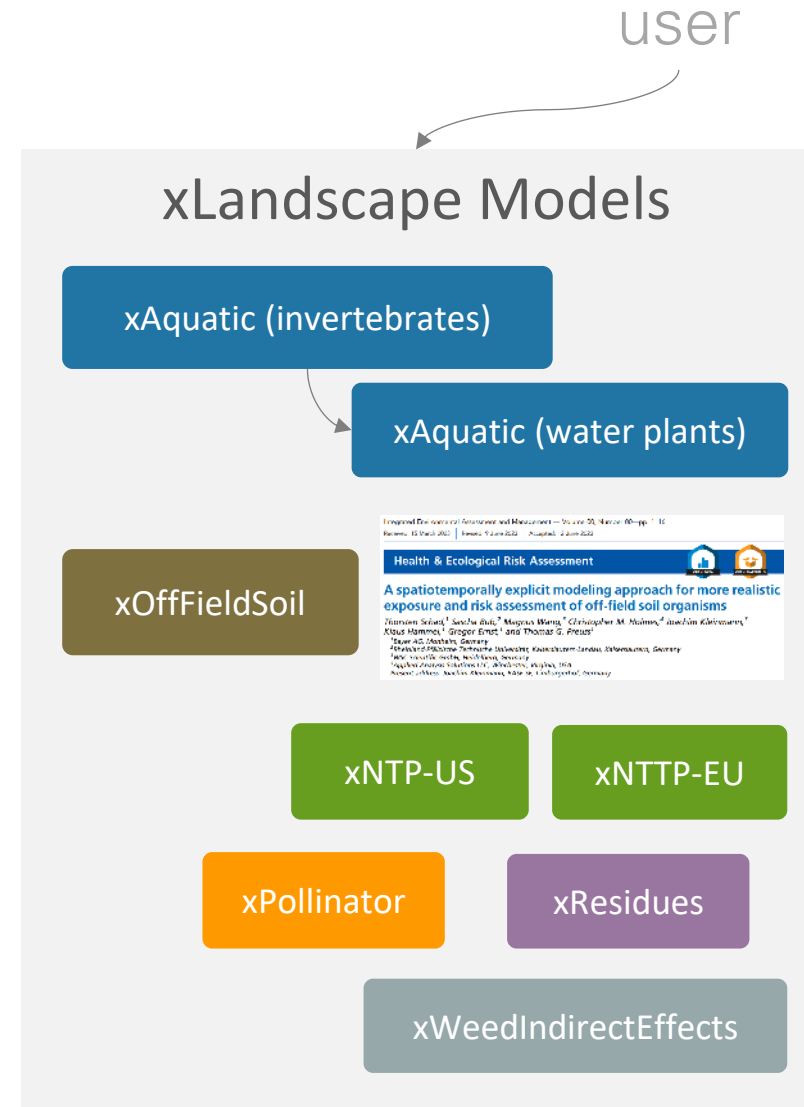
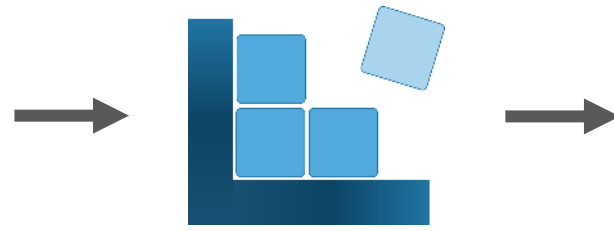
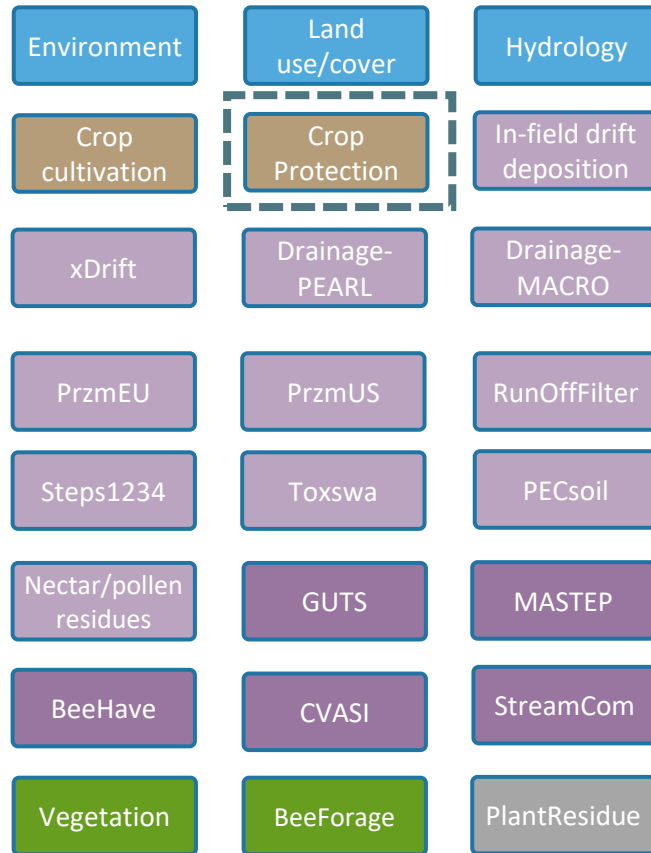


Multidimensional data storage

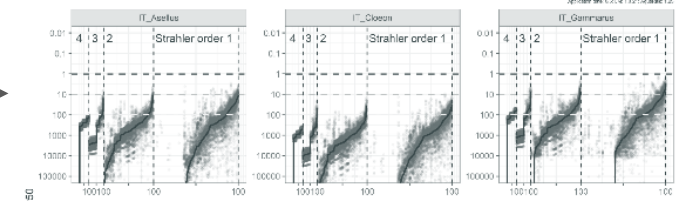
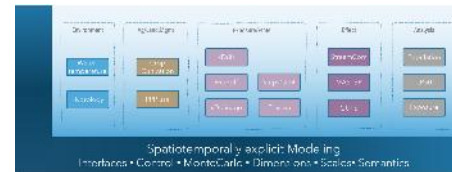
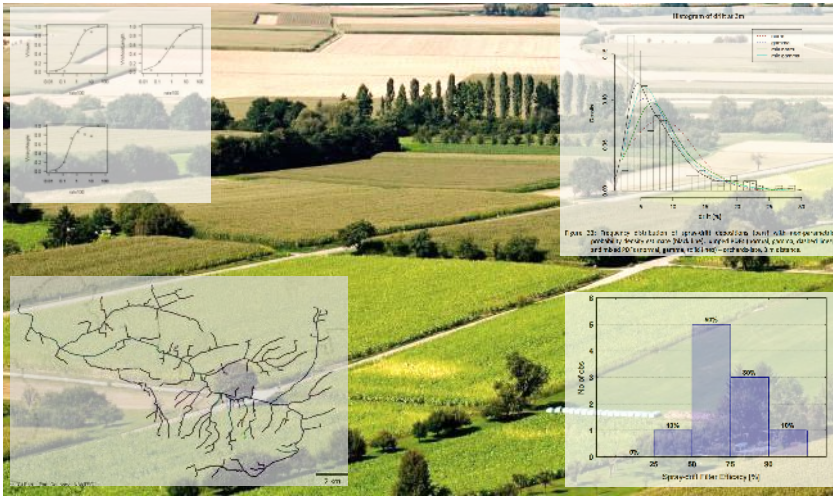
Runtime environments

Libraries (geo,math)

Components & Models



Fundamentals: Propagate real-world variability to model prediction



Hybrid Model (explicit)

- Discretisation (eg, space, time)
- Monte Carlo (PDFs*)

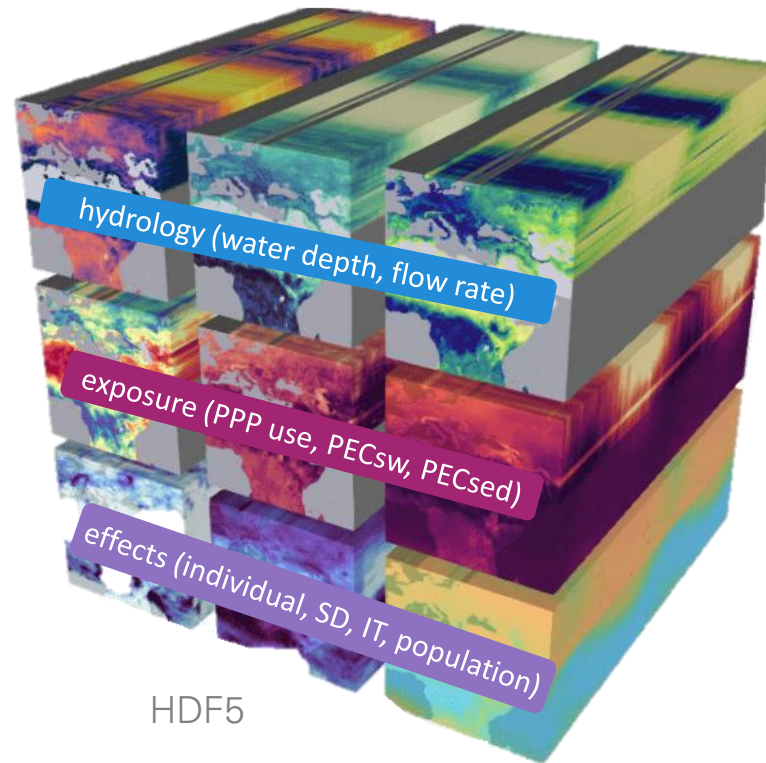
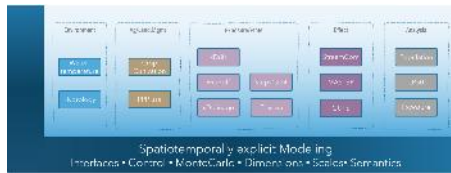
Input variability, eg

- › Agriculture: land use, pesticide use
- › Environment: weather, soil, habitat conditions
- › Biology: species occurrence, life cycle

Output variability, eg

- › Exposure: PECs, residues
- › Effects: mortality, growth, population size
- › Environment: bee forage

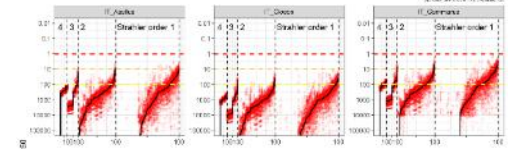
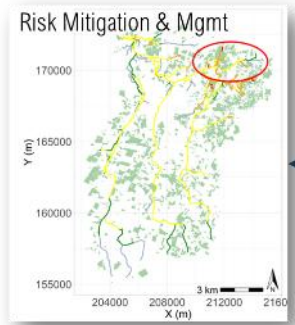
Technology: Multidimensional data arrays



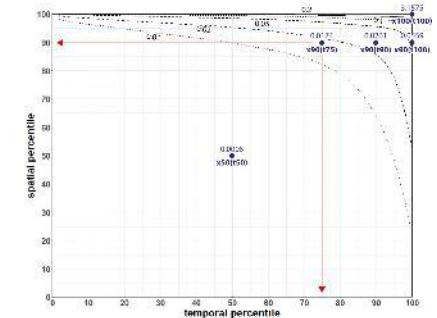
HDF5



R, Python,
Jupyter, Matlab,
Tableau, Knime,
...



	0%	1%	5%	10%	25%	50%	75%	90%	95%	99%	100%
L-08 xp000 5	0.005	0.006	0.008	0.013	0.019	0.025	0.032	0.041	0.051	0.062	0.073
L-10 xp000 11	0.006	0.007	0.012	0.017	0.023	0.031	0.040	0.050	0.061	0.072	0.083
L-11 xp000 12	0.002	0.006	0.013	0.018	0.028	0.051	0.101	0.182	0.254	0.449	1.758
L-21 xp000 13	0.000	0.001	0.011	0.017	0.031	0.066	0.114	0.216	0.305	0.540	2.402
L-08 xp000 8	0.033	0.034	0.035	0.037	0.043	0.056	0.072	0.094	0.125	0.171	0.224
L-10 xp000 11	0.000	0.001	0.004	0.007	0.012	0.023	0.045	0.082	0.115	0.221	1.305
L-11 xp000 12	0.001	0.001	0.005	0.007	0.011	0.021	0.044	0.081	0.111	0.212	1.030
L-11 xp000 13	0.000	0.000	0.008	0.006	0.012	0.024	0.052	0.098	0.141	0.305	1.488
L-08 xp000 8	0.022	0.023	0.024	0.025	0.030	0.039	0.051	0.066	0.082	0.100	0.124
L-10 xp000 11	0.000	0.001	0.002	0.003	0.006	0.012	0.021	0.050	0.070	0.144	0.872
L-11 xp000 12	0.000	0.000	0.002	0.003	0.005	0.011	0.026	0.049	0.070	0.155	0.707
L-11 xp000 13	0.000	0.000	0.001	0.002	0.005	0.013	0.032	0.061	0.091	0.216	0.980
L-08 xp000 8	0.012	0.013	0.014	0.015	0.018	0.023	0.030	0.038	0.047	0.056	0.066
L-10 xp000 11	0.000	0.000	0.001	0.001	0.005	0.011	0.027	0.059	0.085	0.155	0.715
L-11 xp000 12	0.000	0.000	0.000	0.000	0.005	0.013	0.027	0.041	0.051	0.071	0.118
L-11 xp000 13	0.000	0.000	0.000	0.000	0.001	0.006	0.017	0.035	0.054	0.118	0.399



xLandscape User Level and Roles

User - API

- an xLandscape model as backend, called via API (Application Programming Interface)
- also: an xLandscape model as a module, embedded in other environments, eg, DigitalGlobe

find your role

User - Trained

- Trained xLandscape model user, with basic technical expertise, but within the need for expert domain knowledge
- Pre-prepared model parameterisation, execution and compilation of results
- In case, the role might include scenario development, requiring geospatial expertise

User - Expert

- Ready-to-use xLandscape model application (eg, xAquatic), parameterisation (configuration) and execution
- Expert knowledge on xLandscape model domains (eg, xAquatic, xOffFieldSoil, xPollinator)
- In case, the role might include scenario development, requiring geospatial expertise

xLandscape Model Builder

- Expert to build ready-to-use, specific landscape models from using the xLandscape core and components (eg, xOffFieldSoil, xAquatic)
- Note: this role will particularly profit from AI-support

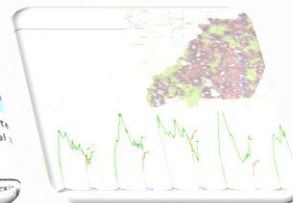
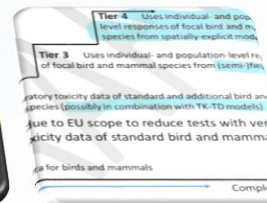
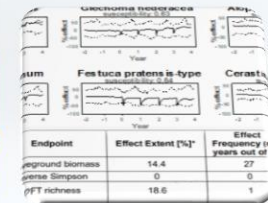
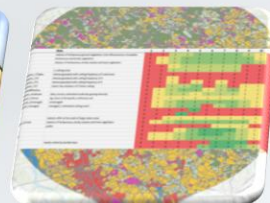
xLandscape Component Developer

- Component developer (integrating models/modules, eg, Toxswa, Guts, StreamCom, Mastep, PRZM, CropProtection)
- Expertise in specific model to be integrated and xLandscape component development (concepts, interface, python)

xLandscape Core Developer

- Core xLandscape developer. Conceptual development and implementation.
- Advanced expertise, eg, risk assessment domain, Informatics, semantics

xLandscape-based Model Examples



Aquatic

- xAquatic
- Catchment-level RA for Invertebrates
- Plants
- Hydrological scenarios
- Ag, Rails, Industrial Vegetation Mgmt

Off-Field-Soil

- xOffFieldSoil
- landscape-level exposure and effects
- addressing the EFSA SO for soil organisms

Pollinator

- xPollinator
- bee forage occurrence in space and time
- Scenarios for BeeHave (ApisRAM)
- work in progress: bee exposure

NTA

- xNTA
- Spatiotemporal exposure pattern, TER, RQ
- work in progress: NTA-Baseline scenarios
- xBembidion Component

NTTP

- xNTTP
- landscape-level exposure, TER, RQ, effects
- link to grassland model IBC
- xNTP-US: refinement to EPA worst-case approach

Insect Decline

- xToxicLoad
- insecticide toxicity
- in space and time
- in landscapes
- due to multiple PPP uses

Birds & Mammals

- Tier4 new EU Guidance
- work in progress

Residues in Plants

- xKnowRes

Next

Community

Users and developers. Connect to research, development and risk assessment teams sharing the demand, thinking and working along the same lines. Trainings. Workshops. Support.

Readyness and Access

Documentation of xLandscape, Components and Scenarios. Testing.
Simple download and getting started. Simple access to case studies, eg via web.
Scenario development.

Adapt AI

AI support and integration in all aspects, eg, building Components, Landscape Models and Scenarios.
Model parameterisation (easy ai-based and formal access to pesticide data), execution and analysis, report writing, etc.

Development

of Components, Models and Scenarios. Maintenance.
xLandscape Version-4: clean architecture (microkernel and component-based software), improved autonomy of components, Digital-twin readiness, coupling of monitoring and modelling for systems-approaches.



Our Values

Openness & Collaboration

We believe in **open source** principles, making our models and components accessible for everyone. This **fosters innovation**, enables **participation**, and ensures that solutions are tailored to real-world challenges rather than built in isolation.

FAIR Principles

We follow the **FAIR guidelines**—Findable, Accessible, Interoperable, and Reusable. By designing modular frameworks and **sharing transparently**, we empower researchers and stakeholders to build on existing work and accelerate progress.

Invitation to Participate

xLandscape development come with a **mindset**. We **invite everyone** to contribute ideas, share expertise and help shaping the future of landscape modelling for sustainable development.



Take Home

xLandscape Modelling = improved **realism & integration**

Modularisation manages complexity and enables **collaboration**

xLandscape = **modular landscape modelling approach**

Components, landscape models, and scenarios can be build for a range of problems. **Open source.**

Our primarily intention is not to establish fixed landscape models

in a sense of building authoritative standards for years (eg as FOCUS models). Yet, even this is possible.

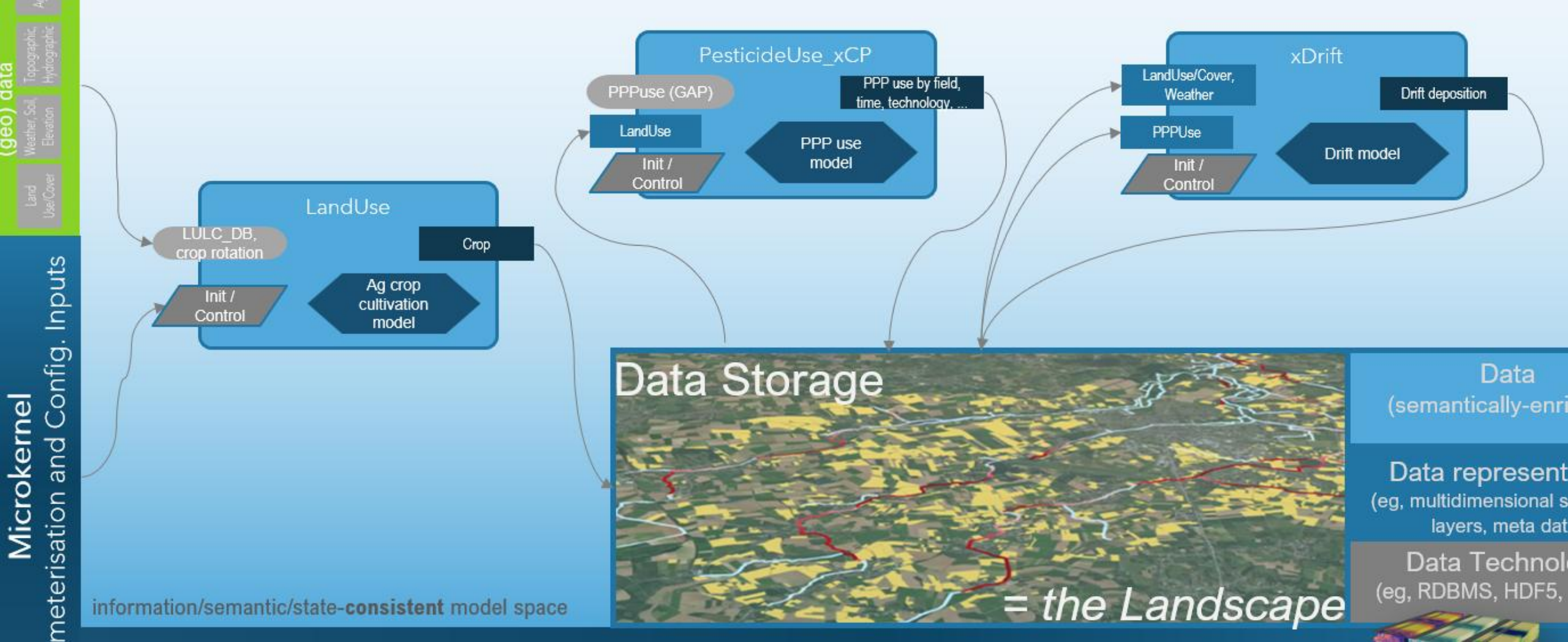
We want to enable building flexible, adaptive research and 'higher-tier' landscape models serving individual problems, of highest possible harmonisation, continuity, and transparency.





Thanks

thorsten.schad@landwerk-ev.de



xLandscape Technical Aspects

Don't be afraid about coding anymore AI is with you (and me)

The screenshot displays the Visual Studio Code interface. The Explorer sidebar on the left shows a project structure for 'XAQUATICRISK'. The main editor window displays an XML file named 'oudebeek_23jul2025_1.xrun'. The XML content is as follows:

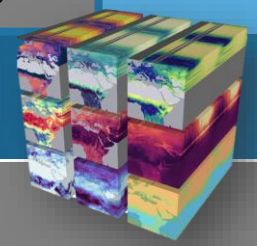
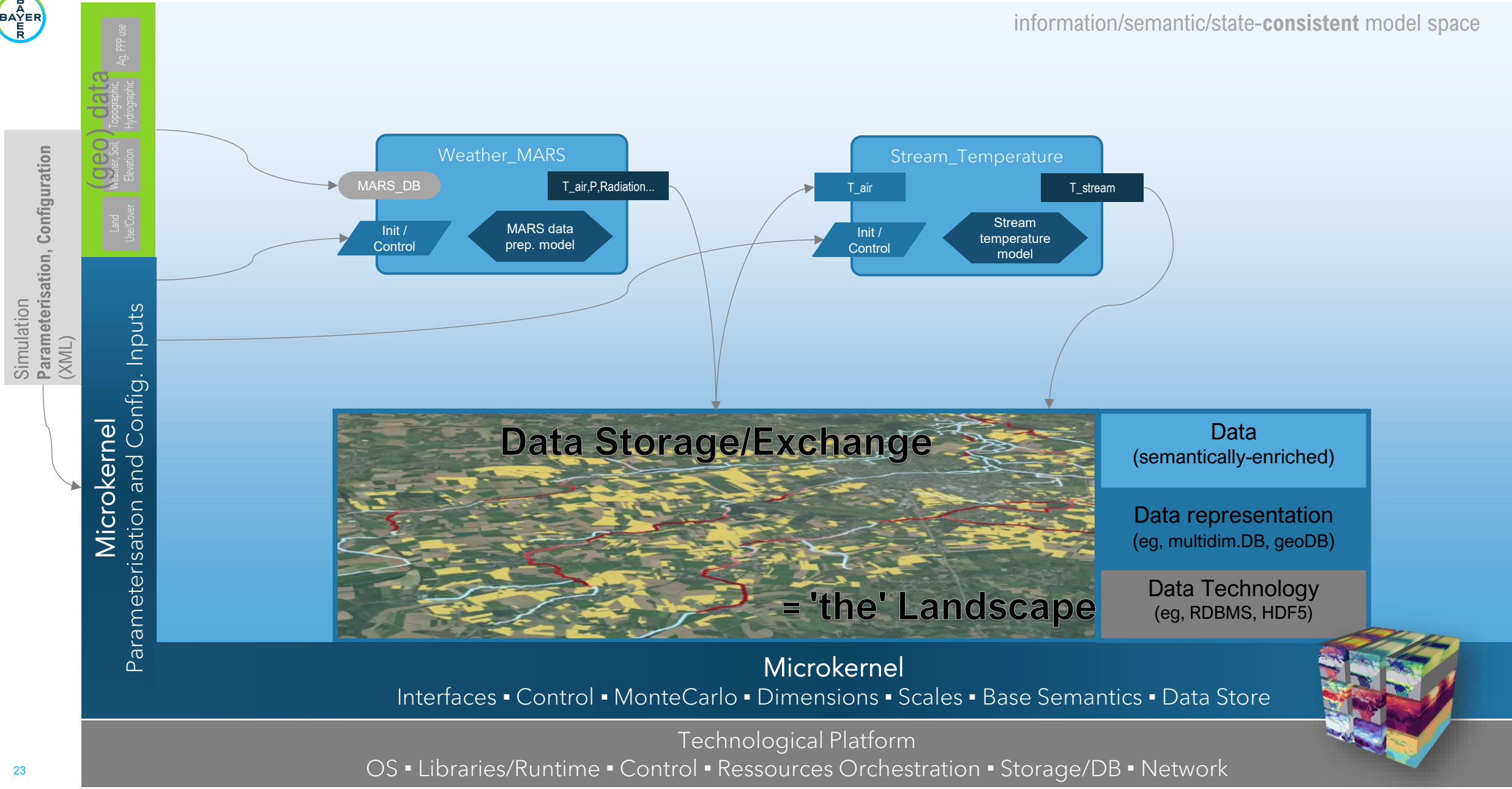
```
<?xml version="1.0" encoding="utf-8"?>
<Parameters
  xmlns="urn:xAquaticRisk"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:schemaLocation="urn:xAquaticRisk model/variant/parameters.xsd">
  <Scenario>
    <!--
    Parameter : Project
    Description : The scenario used by the simulation
    Values : scenario/<xyz> where <xyz> is one of the sub-folders in the scenario folder.
    Remark : Make sure that the scenario is present in the scenario sub-folder.
    -->
    <Project>scenario/Scenario-OudebeekTDI</Project>
  </Scenario>
  <!--
  Parameter : SimulationStart
  Description : The first date that is simulated
  Values : A date of format YYYY-MM-DD within the valid range of dates
  Remark : The valid range of start dates is mainly determined by the input data for the selected scenario.
           The available ranges can be obtained from the scenario documentation.
  -->
  <SimulationStart>1992-01-01</SimulationStart>
  <!--
  Parameter : SimulationEnd
  Description : The last date that is simulated
  Values : A date of format YYYY-MM-DD within the valid range of dates
  Remark : Must be later than the simulation start (or the same date). For limitations of allowed dates, see
           remark for SimulationStart.
  -->
  <SimulationEnd>2017-12-30</SimulationEnd>
</Scenario>
<Pppuse>
  <!--
  Parameter : ApplicationRate
```

The Terminal window at the bottom shows the execution of the command 'C:\LocalWork\XAquaticRisk>_start_.bat oudebeek_23jul2025_1.xrun' and a subsequent Python error: 'FileExistsError: [WinError 183] Cannot create a file when that file already exists: 'C:\LocalWork\XAquaticRisk\run\oudebeek23jul1''. The Chat window on the right provides an 'EXPLANATION OF BATCH COMMAND USAGE' and offers a PowerShell command: 'cmd /c ._start_.bat .\test_oudebeek_1.xrun'.

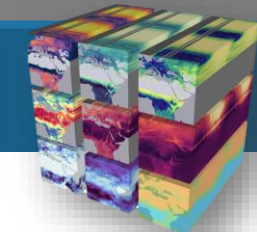
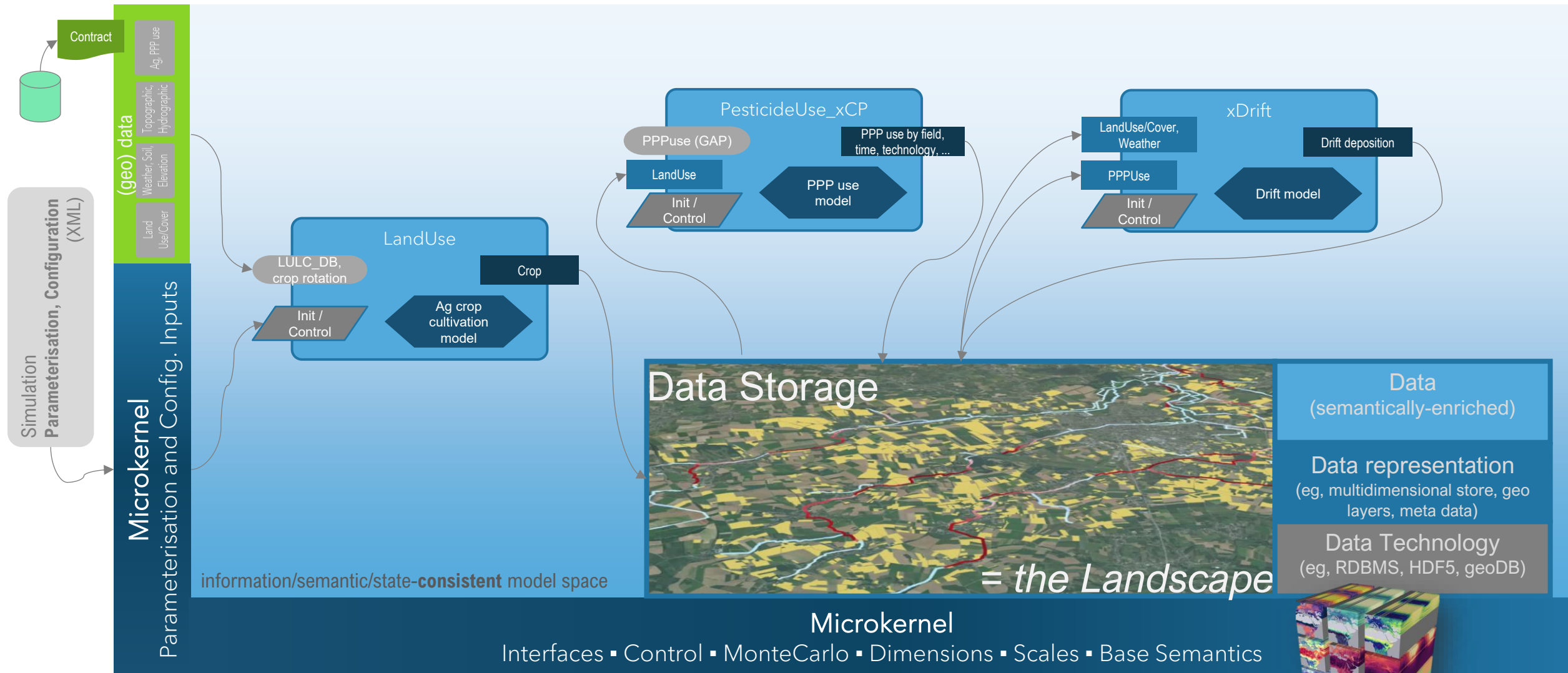
xLandscape Model Building – schematic illustration



information/semantic/state-consistent model space



Microkernel and Components



Components

Definition of inputs and outputs

A component derives from the Component base class

- Components have a set of inputs
- Inputs specify the data that the component needs to run
- Inputs can (and should) be semantically described
- The Landscape Model framework and the model configuration make sure that the inputs are filled with according data (or deviations are handled)

Where to send messages to

Components also have outputs

```
class EnvironmentalFate(base.Component):
    def __init__(self, name: str, default_observer: base.Observer, default_store: typing.Optional[base.Store]) -> None:
        super(EnvironmentalFate, self).__init__(name, default_observer, default_store)
        self._inputs = base.InputContainer(self, inputs: (
            base.Input(
                name: "SprayDriftExposure",
                attributes: (
                    attrib.Class(np.ndarray),
                    attrib.Scales("space_y/1sqm, space_x/1sqm, time/day"),
                    attrib.Unit("g/ha")
                ),
                self.default_observer
            ),
            base.Input(
                name: "RunOffExposure",
                attributes: (
                    attrib.Class(np.ndarray),
                    attrib.Scales("space_y/1sqm, space_x/1sqm, time/day"),
                    attrib.Unit("g/ha")
                ),
                self.default_observer
            ),
            base.Input(
                name: "SoilDT50",
                attributes: (attrib.Class(float), attrib.Scales("global"), attrib.Unit("d")),
                self.default_observer
            )
        ))
        self._outputs = base.OutputContainer(self, outputs: [base.Output(name: "Pec", default_store, self)])
```

The name of the component

Where to send messages to

Where to send data to

The name of the input

The component can specify the data type that it expects

Scales describe the shape of the data: here we expect one value per squaremeter in a regular raster per day

The physical unit of the values

The name of the output

Where to send data to

Model composition

An xLandscape model is build by an XML-based composition

A simulation makes use of

- Components that are run in sequence
- A store that manages the simulation data
- Observers that react on changes in the simulation

All these parts are configurable

The composition defines what components are used by the model and how data is exchanged

The configuration of a component lists the component's inputs and specifies its data

Data can be directly specified in the configuration (scalar and 1-d arrays): attached metadata helps the Landscape Model to check and fulfill requirements

```
<?xml version="1.0" encoding="utf-8"?>
<MCRun>
  <Observers...>
  <Store module="stores" class="X3dfStore"...>
  <Global>
    <SimulationStart>2006-01-01</SimulationStart>
    <SimulationEnd>2015-12-31</SimulationEnd>
  </Global>
  <Composition>
    <Weather module="components" class="MarsWeather"...>
    <LandscapeScenario module="components" class="LandscapeScenario"...>
    <PPM module="components" class="PpmCalendar"...>
    <SprayDrift module="XSprayDrift" class="SprayDrift" enabled="$(SimulateSprayDriftExposure)"...>
    <RunOffPrzm module="RunOffPrzm" class="RunOffPrzm" enabled="$(SimulateRunOffExposure)"...>
    <EnvironmentalFate module="components" class="EnvironmentalFate">
      <SprayDriftExposure>
        <FromOutput component="SprayDrift" output="Exposure" enabled="$(SimulateSprayDriftExposure)"/>
      </SprayDriftExposure>
      <RunOffExposure>
        <FromOutput component="RunOffPrzm" output="Exposure" enabled="$(SimulateRunOffExposure)"/>
      </RunOffExposure>
      <SoilDT50 type="float" unit="d" scales="global">$(DT50)</SoilDT50>
    </EnvironmentalFate>
    <DepositionToPecSoil module="components" class="DepositionToPecSoil"...>
    <DeleteFolder module="components" class="DeleteFolder"...>
  </Composition>
</MCRun>
```

Interfaces

Read and write data

Every component has a run method that is called by the Landscape Model when it is the component's turn in the processing sequence

Inputs have a describe method that gives access to metadata: scales, unit, offsets, element names, geometries...

The read method of inputs loads data (and metadata) from the store into memory; without further specification, all values are read

After reading, the values property contains the actual values

Output values can be directly set or (for large datasets) be prepared

Here, a 3d-NumPy array is prepared (also see scales)

Outputs can (and should) be described in more detail regarding scales, unit, ...

Chunking can be tuned to ensure performant data access and compression

Offsets (among other) help to translate NumPy indices into real-world coordinates

Input data can be read partially using native indices (slices) or real-world coordinates (select)

```
def run(self) -> None:
    """ ... """
    enabled_exposure_inputs = []
    if self.inputs["SprayDriftExposure"].provider is not None:
        enabled_exposure_inputs.append(self.inputs["SprayDriftExposure"])
    if self.inputs["RunOffExposure"].provider is not None:
        enabled_exposure_inputs.append(self.inputs["RunOffExposure"])
    data_set_info = enabled_exposure_inputs[0].describe()
    soil_dt50 = self.inputs["SoilDT50"].read().values
    self.outputs["Pec"].set_values(
        np.ndarray,
        shape=data_set_info["shape"],
        data_type=data_set_info["data_type"],
        chunks=base.chunk_size(chunk=(None, None, 1), data_set_info["shape"]),
        scales="space_y/1sqm, space_x/1sqm, time/day",
        unit="g/ha",
        offset=data_set_info["offsets"]
    )
    pec_current_day = np.zeros(
        shape=(data_set_info["shape"][0], data_set_info["shape"][1], 1), data_set_info["data_type"])
    for t in range(data_set_info["shape"][2]):
        current_slice = (slice(0, data_set_info["shape"][0]), slice(0, data_set_info["shape"][1]), slice(t, t + 1))
        pec_current_day *= math.exp(-math.log(2) / soil_dt50)
        for exposureInput in enabled_exposure_inputs:
            pec_current_day += exposureInput.read(slices=current_slice).values
    self.outputs["Pec"].set_values(pec_current_day, create=False, slices=current_slice, calculate_max=True)
```

Output can be written partially into prepared datasets (create=False) and creation of additional metadata can be controlled

Best Practice

Align with regulatory requirements: Ensure that the modelling approach is consistent with the relevant guidance documents, protection goals, and assessment endpoints for the species group and environmental compartment of interest.

Document the modelling cycle: Provide transparent documentation of the problem definition, model formulation, implementation, parameterization, and validation steps, including sensitivity and uncertainty analyses.

Justify scenario selection: Clearly explain the selection of landscape scenarios, their representativeness, and their applicability to the intended use and region.

Use validated models and data: Employ models that have been evaluated for regulatory use, and use high-quality, representative input data. Where possible, validate model outputs against empirical observations or monitoring data.

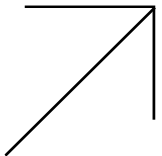
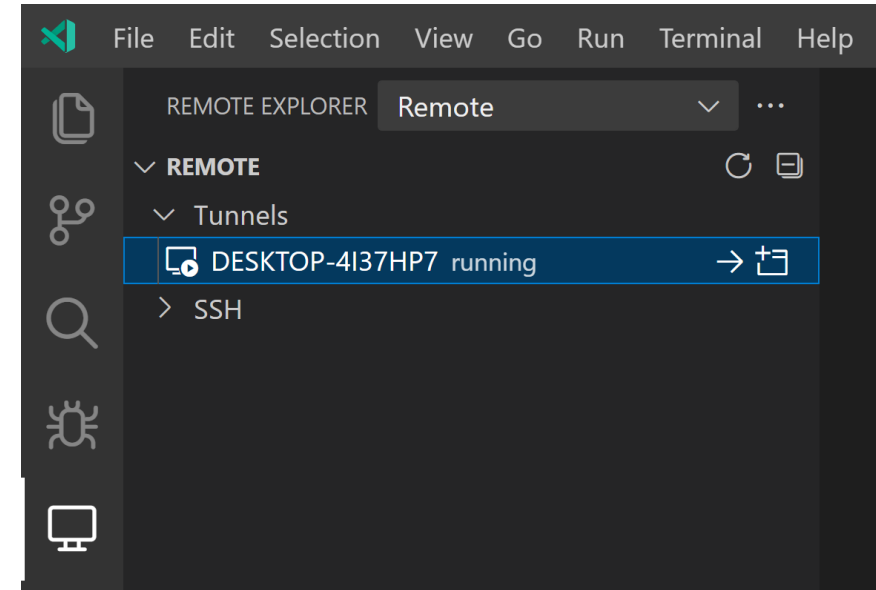
Integrate exposure and effect assessments: Where relevant, link exposure modelling with effect models (e.g., population, food web, agent-based) to provide a holistic assessment of risk and recovery.

Address mitigation and uncertainty: Evaluate the effectiveness of risk mitigation measures in the landscape context, and provide a systematic assessment of uncertainties and their implications for risk characterization.

Engage with EFSA and stakeholders: Participate in pre-submission meetings, public consultations, and stakeholder workshops to ensure alignment with evolving guidance and expectations.

Run your Model on a Backend

VS Code Tunnel





Microkernel Architecture Pattern

Pattern Description

“The Microkernel architectural pattern applies to software systems that must be able to adapt to **changing system requirements**. It separates a minimal functional core from extended functionality and customer-specific parts. The microkernel also serves as **a socket for plugging in these extensions and coordinating their collaboration.**”

1. Microkernel architecture pattern

1. it's not just about linking components (models), **it's about landscape modelling**; this brings the linking of components into a **domain**
 1. modelling happen in a 'geographic world' (coordinate system)
 2. space and time → spatiotemporally explicit
 3. scales → scale-explicit

2. Minimum Kernel Functionality

1. Component control
2. Client adapter
3. storage
4. isolation, processes, scheduling
5. messages

Pattern Description

